



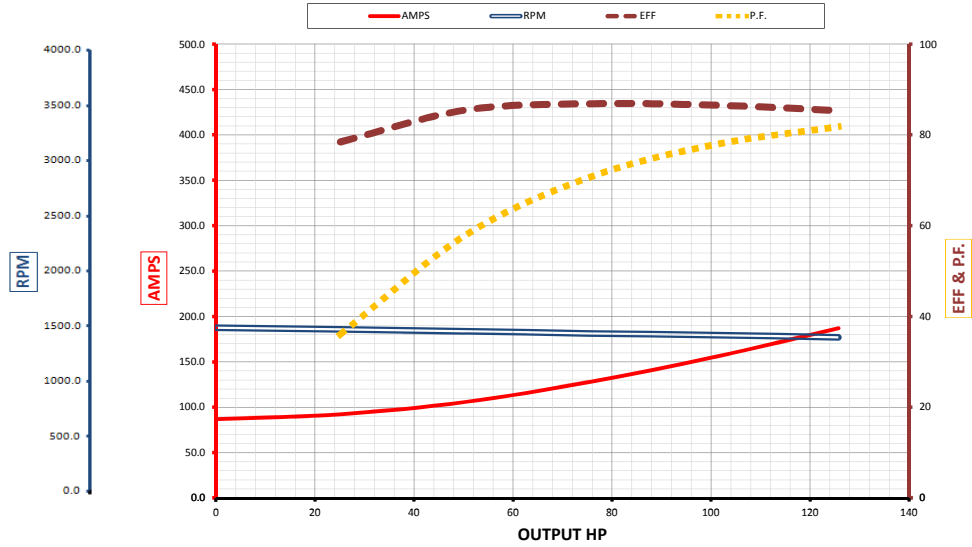
MOTOR PERFORMANCE DATA

Model: 10" 4P Submersible Motor

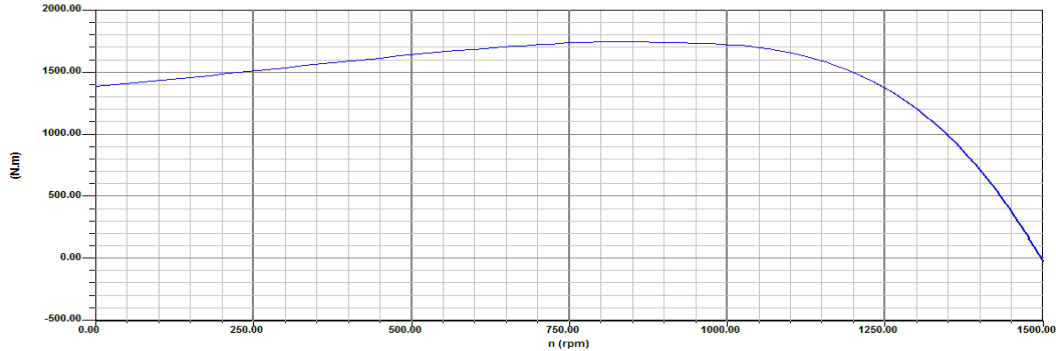
<u>WATER</u>	Type	<u>100</u>	HP	<u>155</u>	AMPS
<u>3</u>	Phase	<u>415</u>	Volt	<u>1435</u>	RPM
<u>1.15</u>	S.F.	<u>30Deg.C</u>	Max.Amb.Water	<u>50</u>	Hertz
				<u>4540</u>	Kg Thrust Load

Date: <u>18/06/2014</u>	
<u>100</u>	HP
<u>1435</u>	RPM
<u>1000</u>	mm Stack

			Load	KW out	HP	KW in	EFF	P.F.	RPM	AMPS
Full Load Torque	<u>500</u>	Nm	No Load	0.0	0	4	0	<u>0.06</u>	<u>1500</u>	<u>87.0</u>
Break Down Torque	<u>1746</u>	Nm	25%	18.8	25	24	78.5	<u>0.36</u>	<u>1485</u>	<u>92.4</u>
Locked Rotor Torque	<u>1387</u>	Nm	50%	37.5	50	44	85.4	<u>0.58</u>	<u>1470</u>	<u>105.8</u>
Locked Rotor Current	<u>931</u>	Amps	75%	56.3	75	65	86.8	<u>0.71</u>	<u>1450</u>	<u>127.8</u>
Winding Resistance	<u>0.12</u>	Ohms	100%	75.0	101	87	86.5	<u>0.78</u>	<u>1435</u>	<u>155.2</u>
Weight (With Water)	<u>520</u>	Kg (Approximate)	125%	93.8	126	110	85.3	<u>0.82</u>	<u>1415</u>	<u>186.9</u>



OUTPUT TORQUE VS SPEED



ADDITIONAL INPUT WATTS DUE TO THRUST

